

IN THE CLAIMS:

Claims 2-5, 11, 14, 16, 17, 19, and 22 have been canceled.

Claims 1, 6-10, 12-13, 15, 18, 20, 21, and 23-39 have been allowed.

1. (Allowed) A turkey decoy, comprising:
a flexible skin covering at least a portion of said turkey decoy ;
a robotic frame for supporting said at least a portion of said turkey decoy, said robotic frame further, comprising:
 - 1) a mobile carriage mounting to a mobile base for traversing over the ground surface;
 - 2) at least one post projecting upwardly from said mobile carriage;
 - 3) a central frame member supported on said least one post having a vertical axis defining a body;
 - 4) a neck supporting frame portion mounting on said central frame member projecting from a first end thereof;
 - 5) a tail supporting frame portion pivotally secured to said central frame member projecting from a second end thereof said tail supporting frame portion defining a tail of said turkey decoy including at least a pair of tail members moveable relative to one another for selectively varying the width of said tail of said turkey decoy;
 - 6) a first pair of moveable arms mounted on said central frame member for supporting a pair of wing defining portions of said turkey decoy;
 - 7) at least one remotely actuated motor for driving said mobile base;
 - 8) a second remotely actuated motor in cooperative engagement with said tail supporting frame for moving said tail up and down and/or for moving said at least a pair of tail members relative to one another; and
 - (9) a third remotely actuated motor for rotating said body of said turkey decoy about the vertical axis of said at least one post; and
 - 10) said remotely actuated motors being powered by at least one battery mounting on said mobile carriage and being controlled by an RF receiver mounted thereon in communication with a

remotely located hand held RF transmitter.

2. (Cancel) The robotic frame as defined in claim 1, wherein at least one of said first and second frame portions and said first pair of arms are movably mounted on said central frame portion.

3. (Cancel) The robotic frame as defined in claim 2, wherein each of said first and second frame portions and said first pair of arms are pivotally mounted on said central frame portion.

4. (Cancel) The robotic frame as defined in claim 1, including a remotely controlled motor means mounted on said carriage and means drivingly connecting the same to said ground traversing means.

5. (Cancel) The robotic frame as defined in claim 1, including means on a portion thereof for reorienting at least a portion thereof to selectively change the direction that the turkey decoy faces.

6. (Allowed) The turkey decoy as defined in claim 1, including means pivotally mounting said central frame member on said at least one post for rotation about a vertical axis and thereby providing means to change the direction that said turkey decoy faces.

7. (Allowed) The turkey decoy as defined in claim 6, including remotely actuated motor means carried by said robotic frame and drivingly connected to controllably rotate said central frame member on said at least one post.

8. (Allowed) The turkey decoy as defined in claim 1, including at least one reversible independently controlled motor means mounted on each side of said mobile carriage, means drivingly connecting said reversible independently controlled motors to a ground traversing means thereon and means for selectively controlling said reversible independently controlled motors to cause said mobile carriage to travel over the ground surface and change the direction of travel and

thereby reorient the turkey decoy to face a desired direction.

9. (Allowed) The robotic frame turkey decoy frame as defined in claim 1, wherein said neck defining supporting frame portion is pivotally mounted on said central frame member.

10. (Allowed) The turkey decoy as defined in claim 1, wherein said first pair of moveable arms are pivotally mounted on said central frame member for movement relative thereto.

11. (Cancel) The robotic frame as defined in claim 10, wherein said first pair of arms are pivotally mounted on said central frame portion.

12. (Allowed) The turkey decoy as defined in claim 1, including a second pair of moveable arms and means for movably mounting same on said central frame member.

13. (Allowed) The turkey decoy as defined in claim 12, including means interconnecting said first pair of moveable arms and said second pair of moveable arms for interrelating movement therebetween.

14. (Cancel) The robotic frame as defined in claim 1, wherein said second frame portion defines a tail of the turkey decoy and includes a pair of members moveable relative to one another for selectively varying the width of the tail of the decoy.

15. (Allowed) The turkey decoy as defined in claim 1, including means pivotally mounting said at least a pair of tail members on said central frame member to pivot about a generally horizontal axis and change the inclination of said tail of the turkey decoy.

16. (Cancel) The robotic frame as defined in claim 1, including a flexible covering mounted on said frame and thereby providing a mobile turkey decoy having a body, a neck with a head thereon projecting from one end of the body and a tail projecting from the other end of the body

and wherein each of the head and tail are moveable up and down in a vertical direction.

17. (Cancel) The turkey decoy as defined in claim 1, including motor means on said frame and drivingly connected to said movable frame portions for selectively moving the same.

18. (Allowed) The turkey decoy as defined in claim 1, wherein said remotely actuated motor comprises a servo motor mounted on said central frame member, wherein said neck supporting frame portion and said tail supporting frame portion and said first pair of moveable arms are movable relative to said central frame portion member and means drivingly connecting said servo motor to move same in co-ordinated interrelated relationship.

19. (Cancel) The turkey decoy as defined in claim 18, including an RF receiver mounted thereon and connected to said motor for use in remote control of the same.

20. (Allowed) The turkey decoy as defined in claim 1, including a second pair of moveable arms and means moveably mounting same on said central frame member, located to engage a turkey back defining portion for moving same.

21. (Allowed) The turkey decoy as defined in claim 20, including means for interconnecting said first pair of moveable arms and said second pair of moveable arms to interrelate movement of same.

22. (Cancel) The turkey decoy as defined in Claim 1, including a central processing unit electrically connecting to and communicating with said servo units for selecting programming movement sequences programmable by a keypad or insertion of a removable readable memory device.

23. (Allowed) The turkey decoy as defined in claim 1, including a speaker and recording device activated by a timer device or remote unit.

24. (Allowed) A robotic frame for supporting a covering to provide a turkey decoy, comprising:

a flexible skin covering at least a portion of said turkey decoy ;

a robotic frame for supporting said at least a portion of said turkey decoy, said robotic frame further, comprising:

a) a mobile carriage mounting to a mobile base having means mounted thereon for traversing over the ground surface;

b) at least one post having a vertical axis projecting upwardly from said mobile carriage;

c) a central frame member supported on said least one post defining a body;

d) a neck supporting frame portion mounting on said central frame member portion and projecting from a first end thereof;

e) a tail supporting frame portion pivotally secured to said central frame member projecting from a second end thereof, said tail supporting frame portion defining a tail of said turkey decoy including at least a pair of tail members moveable relative to one another for selectively varying the width of said tail of said turkey decoy;

f) a first pair of moveable arms mounted on said central frame member for supporting a pair of wing defining portions of said turkey decoy;

g) at least one servo motor for driving said mobile base;

h) a second servo motor in cooperative engagement with said tail supporting frame for moving said tail up and down and/or for moving said at least a pair of tail members relative to one another;

j) a third servo motor for rotating said body of said turkey decoy about the vertical axis of said at least one post;

k) said servo motors being powered by at least one battery mounting on said mobile carrier in electrical communication therewith; and

j) including a central processing unit electrically connecting to and communicating with said selected servo motor for selecting programming movement sequences programmable by a keypad or insertion of a removable readable memory device.

25. (Allowed) The turkey decoy as defined in claim 24, including means pivotally mounting said central frame member on said at least one post for rotation about the vertical axis and thereby providing means to change the direction that said turkey decoy faces.

26. (Allowed) The turkey decoy as defined in claim 25, including remotely actuated motor means carried by said robotic frame and drivingly connected to controllably rotate said central frame member on said at least one post.

27. (Allowed) The turkey decoy as defined in claim 24, including reversible independently controlled motor means mounted on each side of said mobile carriage, means drivingly connecting said reversible independently controlled motors to said ground traversing means thereon and means for selectively controlling said reversible independently controlled motors to cause said mobile carriage to travel over the ground surface and change the direction of travel and thereby reorient the turkey decoy to face a desired direction.

28. (Allowed) The turkey decoy as defined in claim 24, wherein said neck supporting frame portion is pivotally mounted on said central frame member.

29. (Allowed) The turkey decoy as defined in claim 24, wherein said first pair of moveable arms are pivotally mounted on said central frame member for movement relative thereto.

30. (Allowed) The turkey decoy as defined in claim 24, including a second pair of moveable arms and means for movably mounting same on said central frame member.

31. (Allowed) The turkey decoy as defined in claim 30, including means interconnecting said first pair of moveable arms and said second pair of moveable arms for inter relating movement therebetween of the same.

32. (Allowed) The turkey decoy as defined in claim 24, including means pivotally mounting

said at least a pair of tail members on a central frame member to pivot about a generally horizontal axis and change the inclination of said tail of said turkey decoy.

33. (Allowed) The turkey decoy as defined in claim 24, wherein a remotely activated motor comprises a servo motor mounted on said central frame member, wherein said neck supporting frame portion and said tail supporting frame portion and said first pair of moveable arms are movable relative to said central frame member and means drivingly connecting said servo motor to move same in co-ordinated interrelated relationship.

34. (Allowed) The turkey decoy as defined in claim 24, including a second pair of moveable arms and means moveably mounting same on said central frame member, located to engage a turkey back defining portion for moving same.

35. (Allowed) The turkey decoy as defined in claim 35, including means for interconnecting said first pair of moveable arms and said second pair of moveable arms to interrelate movement of same.

36. (Allowed) The turkey decoy as defined in claim 24, including a speaker and recording device activated by a timer device.

37. (Allowed) A robotic frame for supporting a covering to provide a turkey decoy, comprising:

- a flexible skin covering at least a portion of said turkey decoy ;

- a robotic frame for supporting said at least a portion of said turkey decoy, said robotic frame further, comprising:

- a) a mobile carriage having a vertical axis mounting to a mobile base having means mounted thereon for traversing over the ground surface;

- b) means for rotatably supporting said mobile carriage extending upwardly from said mobile base;

- c) a central frame member supported on said rotatable supporting means defining a body;
- d) a neck supporting frame portion mounting on said central frame member portion and projecting from a first end thereof;
- e) a tail supporting frame portion pivotally secured to said central frame member projecting from a second end thereof, said tail supporting frame portion defining a tail of said turkey decoy including at least a pair of tail members moveable relative to one another for selectively varying the width of said tail of said turkey decoy;
- f) a first pair of moveable arms mounted on said central frame member for supporting a pair of wing defining portions of said turkey decoy;
- g) at least one servo motor for driving said mobile base;
- h) a second servo motor in cooperative engagement with said tail supporting frame for moving said tail up and down and/or for moving said at least a pair of tail members relative to one another;
- j) a third servo motor for rotating said body of said turkey decoy about the vertical axis of said rotatable supporting means;
- k) said servo motors being powered by at least one battery mounting on said mobile carriage in electrical communication therewith; and
- j) including a central processing unit electrically connecting to and communicating with a selected servo motor for selecting programming movement sequences programmable by a keypad or insertion of a removable readable memory device or said servo motors being controlled by an RF receiver mounted thereon in communication with a remotely located hand held RF transmitter.

38. (Allowed) The turkey decoy as defined in claim 38, including a speaker and recording device activated by a timer device or remote unit.

39. (New) The turkey decoy as defined in claim 38, wherein said means for rotatably supporting is a post.

Please add the following new claims:

40. (New) A frame for supporting a covering to provide a turkey decoy, comprising:
a flexible skin covering at least a portion of said turkey decoy ;
a frame for supporting said at least a portion of said turkey decoy, said frame further, comprising:
a neck supporting frame portion mounting on a central frame member portion and projecting from a first end thereof;
a tail supporting frame portion pivotally secured to said central frame member projecting from a second end thereof, said tail supporting frame portion defining a tail of said turkey decoy including at least a pair of tail members moveable relative to one another for selectively varying the width of said tail of said turkey decoy;
at least one servo motor in cooperative engagement with said tail supporting frame for moving said tail up and down and/or for moving said at least a pair of tail members relative to one another;
said servo motor being powered by at least one battery mounting on said mobile carriage in electrical communication therewith; and
means for actuating said servo motor.

41. (New) The turkey decoy as defined in claim 40 further comprising a mobile carriage having a vertical axis mounting to a mobile base having means mounted thereon for traversing over the ground surface.

42. (New) The turkey decoy of claim 41 including at least one servo motor for driving said mobile base;

43. (New) The turkey decoy as defined in claim 41 including means for rotatably supporting said mobile carriage extending upwardly from said mobile base.

44. (New) The turkey decoy of claim 43 including at least one servo motor for driving said means for rotatably supporting said mobile carriage.

45. (New) The turkey decoy as defined in claim 40 including a pair of arms mounted on said central frame member for supporting a pair of wing defining portions of said turkey decoy.

46. (New) The turkey decoy as defined in claim 45 wherein said arms are movable.

47. (New) The turkey decoy as defined in claim 46 including means for moving said arms.

48. (New) The turkey decoy as defined in claim 45 wherein said means for moving said arms is at least one servo motor.

49. (New) the turkey decoy as defined in claim 40 wherein said servo motor is powered by at least one battery mounting on said mobile carriage in electrical communication therewith.

50. (New) The turkey decoy as defined in claim 40 further comprising a central processing unit electrically connecting to and communicating with a selected servo motor for selecting programming movement sequences programmable by a keypad or insertion of a removable readable memory device or said servo motors being controlled by an RF receiver mounted thereon in communication with a remotely located hand held RF transmitter.